# Modern trends <br> in discrete mathematics and computer science 

Formal correctness proofs for sequential programs

Lecturer:<br>Vladislav Podymov<br>E-mail:<br>valdus@yandex.ru

## Introduction

Consider the following fragment of a program in C syntax:

```
int * a;
int n;
..
int s = 0;
for(int i = 0; i < n; ++i) s = s + a[i];
```


## What does this fragment do?

The most obvious answer is:
it computes the sum of the elements of a and stores it to s
A less obvious better answer is:
if the data is okay at the beginning of the loop, then it computes the sum ...

## Is it the most correct answer?

Not so simple: it implicitly assumes that the meaning of the program complies with the C standard

## Introduction

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```

How to prove that a program behaves the way it should?
(in general, maybe even non-standard, or non-C-like)

To do it, we need a lot of mathematics:

- What is a program? (syntax)
- What is a behavior of a program? (semantics)
- How to define a desired behavior?
(borderline between semantics and proof systems)
- What is a legitimate proof? (proof systems)
- Can we even prove anything useful? (properties of proof systems)


## Introduction

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```

The main focus is on while programs: a simplistic mathematical model intended to capture core features of all sequential programs

Though "while programs" is a certain specific model, note that it provides a general mathematical machinery which allows to (at least) describe and (at most) analyze all kinds of programs

General and specific pieces of this machinery are mixed together in the talk, and separated and pointed out whenever possible

## Syntax: types

Program data are usually typed (whatever it means)

A type is a name of a set of legitimate data values

While programs use two sorts of types:

- a basic type is a type of a primitive chunk of data
- whatever "primitive" means: bounded or unbounded numbers, plain pointers, structures, ...
- Boolean is a always assumed to be a basic type of Boolean values
- integer, when mentioned, is assumed to be a basic type of all integer numbers
- a higher type is used to denote arrays and functions:
- $T_{1} \times \cdots \times T_{n} \rightarrow T$, where $T_{1}, \ldots, T_{n}, T$ are basic types, and $n \geq 1$
- $n$ is the arity of the type


## Syntax: variables, constants

A variable is a name (symbol) which denotes a chunk of data of a certain type: the data can be accessed to and modified by a program via its name

A simple variable is a variable of a basic type
An array variable is a variable of a higher type
Var is the set of all variables

A constant is a name which denotes a certain value of a certain type
A simple constant is a constant of a basic type
A functional symbol is a constant of a higher type
A relational symbol is a functional constant of a type

$$
T_{1} \times \cdots \times T_{n} \rightarrow \text { Boolean }
$$

Const is the set of all constants

## Syntax: typical constants

true, false are simple constants of the Boolean type
$0,1,-1,2,-2, \ldots$ are simple constants of the integer type
$<, \leq,>, \geq,=, \neq, \ldots$ are relational symbols of the type integer $\times$ integer $\rightarrow$ Boolean
$+,-, *, /, \ldots$ are functional symbols of the type integer $\times$ integer $\rightarrow$ integer
$\&, \vee, \neg, \rightarrow, \ldots$ are relational symbols of the type Boolean $\times$ Boolean $\rightarrow$ Boolean

## Syntax: expressions

$$
\text { Example: } x+1<y
$$

An expression of a type $T$ :

- is a string constructed from variables and constants with respect to their types and arities
- intuitively, for certain current data values provides a value of the type $T$
- not a definition: what do "a value" and "provides" mean?

Backus-Naur form (BNF) for an expression ( $\varepsilon$ ):

$$
\varepsilon::=c|x| a\left[\varepsilon_{1}, \ldots, \varepsilon_{n}\right] \mid f\left(\varepsilon_{1}, \ldots, \varepsilon_{n}\right)
$$

- $c$ is a simple constant
- $x$ is a simple variable
- $a$ is an array variable of a type $T_{1} \times \cdots \times T_{n} \rightarrow T$
- $f$ is a functional symbol of a type $T_{1} \times \cdots \times T_{n} \rightarrow T$
- $\varepsilon_{i}$ is an expression of the type $T_{i}$
- $a\left[\varepsilon_{1}, \ldots, \varepsilon_{n}\right]$ and $f\left(\varepsilon_{1}, \ldots, \varepsilon_{n}\right)$ are expressions of the type $T$

Infix notation for binary functional symbols:

$$
\oplus\left(\varepsilon_{1}, \varepsilon_{2}\right) \text { equals to }\left(\varepsilon_{1} \oplus \varepsilon_{2}\right)
$$

## Syntax: subscripted variables, programs

An expression of the form $a\left[\varepsilon_{1}, \ldots, \varepsilon_{n}\right]$ is a subscripted variable:

- it is not a variable "in the full sense"
- it refers to a primitive chunk of data (just like a nonsubscripted variable)
BNF for a program $(\pi)$ :

$$
\begin{array}{lll}
\pi & ::= & \text { stmt | } \operatorname{stmt} \pi \\
\text { stmt }::= & \text { skip; | } x:=\varepsilon_{x} ; \mid \\
& \text { if } \varepsilon_{b} \text { then } \pi \text { else } \pi \text { fi; | while } \varepsilon_{b} \text { do } \pi \text { od; }
\end{array}
$$

- stmt is a statement
- a program is a nonempty sequence of statements
- any statement is a program
- $x$ is a subscripted variable
- $\varepsilon_{x}$ is an expression of the same type as $x$
- $\varepsilon_{b}$ is a Boolean expression
$\Pi$ is the set of all programs


## Syntax: programs

$\pi_{1}: \quad a b c d$
$\pi_{2}$ : skip;
$\pi_{3}$ : if $b \vee c[3]$ then $x[y[z], 1]:=z ; z:=2$; else skip; fi;
$\pi_{1}$ is not a program
$\pi_{2}$ is a program
$\pi_{3}$ is a program iff

1. $b$ is a simple Boolean variable
2. $c$ is a variable of the type integer $\rightarrow$ Boolean
3. $z$ is a simple integer variable
4. $y$ is a variable of a type integer $\rightarrow T$
5. $x$ is a variable of the type $T \times$ integer $\rightarrow$ integer

## Semantics

$$
\text { if } b \vee c[3] \text { then } x[y[z], 1]:=z ; z:=2 \text {; else skip; fi; }
$$

At this point we are able to distinguish programs from non-programs, but know nothing about their meaning (semantics):

- What "values" a program works with, and how these values are related to types
- What value is "provided" by an expression
- What does each statement of a program mean
- How the meanings of statements are combined into the meaning of the whole program


## Semantics: values, domains

A domain $D_{T}$ of a type $T$ is a set of values of this type
To specify a certain domain, we should at least

- pick a certain programming language
- determine a goal of a program analysis
- for instance, if we do not care about extreme overflow cases usual for "real" modular arithmetic, then we may use a "simplified" unbounded arithmetic instead

For while programs, the following domains are fixed:

- $D_{\text {Boolean }}=\{$ true, false $\}$
- $D_{\text {integer }}=\{0,1,-1,2,-2, \ldots\}$
- $D_{T_{1} \times \cdots \times T_{n} \rightarrow T}$ is the set of all functions from the Cartesian product $D_{T_{1}} \times \cdots \times D_{T_{n}}$ into the set $D_{T}$

A semantic domain $D$ is a disjoint union of domains of all types

## Semantics: interpretations

Given a set of constants, a set of types, and type domains, an interpretation $\mathcal{I}$ is a mapping of every constant of every type $T$ to an element of $D_{T}$

An interpretation is a natural mathematical way to define a "static" semantical part of a programming language: the meaning of constants, operations, predefined functions, ...

For instance, a typical (but not the only) interpretation $\mathcal{I}$ of Boolean-related and integer-related constants is defined as follows:

- each simple constant, Boolean or integer, is mapped into itself:
- $\mathcal{I}($ true $)=$ true $, \mathcal{I}(2)=2, \ldots$
- each typical functional symbol is mapped into a function in a natural way:
- $\mathcal{I}(\vee)($ true, false $)=$ true
- $\mathcal{I}(+)(2,3)=5$
- $\mathcal{I}(<)(5,2)=$ false
- ...


## Semantics: data states

## A data state is

- (informally) a collection of values stored at any given time in all data chunks managed by a program (and accessed via variable names)
- (formally) a mapping $\sigma: \operatorname{Var} \rightarrow D$, such that for each variable of a type $T, \sigma(x)$ is a value of the domain $D_{T}$

A data state is a "dynamic" part of a programming language: an execution of a sequential program is a stepwise modification of a current data state
$\Sigma$ is the set of all data states
$\left\{x_{1} / v a l_{1}, \ldots, x_{n} / v a l_{n}\right\}$ is a state $\sigma$ such that $\operatorname{Var}=\left\{x_{1}, \ldots, x_{n}\right\}$, and $\sigma\left(x_{i}\right)=v a l_{i}$ for each $i, 1 \leq i \leq n$

## Semantics: expressions

$$
x+3
$$

Now, having a huge spectre of definitions, we finally can answer the (apparently, not so simple) question
"What does an expression mean?"
First of all, we pick a certain programming language, and fix its "static" part

- mathematically, we assume an interpretation $\mathcal{I}$ to be given

A value provided by an expression is fully defined by a data state obtained at a given execution time

- mathematically, the semantics of an expression $\varepsilon$ of a type $T$ is the following mapping $\mathcal{I} \llbracket \varepsilon \rrbracket: \Sigma \rightarrow D_{T}$ :
- for each simple constant $c, \mathcal{I} \llbracket c \rrbracket(\sigma)=\mathcal{I}(c)$
- for each simple variable $x, \mathcal{I} \llbracket x \rrbracket(\sigma)=\sigma(x)$
- for each expression $\varepsilon$ of the form $a\left[\varepsilon_{1}, \ldots, \varepsilon_{n}\right]$,

$$
\mathcal{I} \llbracket \varepsilon \rrbracket(\sigma)=\sigma(a)\left(\mathcal{I} \llbracket \varepsilon_{1} \rrbracket(\sigma), \ldots, \mathcal{I} \llbracket \varepsilon_{n} \rrbracket(\sigma)\right)
$$

- for each expression $\varepsilon$ of the form $f\left(\varepsilon_{1}, \ldots, \varepsilon_{n}\right)$,

$$
\mathcal{I} \llbracket \varepsilon \rrbracket(\sigma)=\mathcal{I}(f)\left(\mathcal{I} \llbracket \varepsilon_{1} \rrbracket(\sigma), \ldots, \mathcal{I} \llbracket \varepsilon_{n} \rrbracket(\sigma)\right)
$$

## Semantics: variety of definition approaches

$\pi$ : if $b$ then $x:=x+1$; else skip; fi;
The next question is:
"What does a program mean?"
First of all, the main purpose of a (sequential) program is to

- take some initial data values (input data state)
- process these values
- provide some final data values depending on the initial ones (output data state)
"To define the meaning of a program" basically means "to define a relation between input and output data states"
- mathematically, the semantics of a program $\pi$ is a relation $\mathcal{I} \llbracket \pi \rrbracket \subseteq \Sigma \times \Sigma$ between input and output data states
- for some programming languages this relation is a total function, for some - a partial function, for some - a multivalued function (i.e. relation in a full sense)


## Semantics: variety of definition approaches

$\pi$ : if $b$ then $x:=x+1$; else skip; $\mathbf{f i}$;
Even when a programming language is picked, a lot of approaches exist on how to define a semantics of a program

The most popular ones are:

- operational approach
- a data state is modified step by step during a statement execution in the following way: ...
- the next statement to be executed after the current statement is: ...
- if a stepwise statement execution is finished, then the output state is: ...


## Semantics: variety of definition approaches

$\pi$ : if $b$ then $x:=x+1$; else skip; $\mathbf{f i}$;
Even when a programming language is picked, a lot of approaches exist on how to define a semantics of a program

The most popular ones are:

- denotational approach
- semantics of a primitive statement is the following binary relation over data states: ...
- the relation is represented as a formula of a language designed specifically for declarative description of computable relations
- semantics of a complex statement is the following composition of relations: ...
- the composition is a simple syntactic modification of given formulae which declaratively describes some nontrivial transformations over relations
- for instance, a minimization operator for $\mu$-recursive functions is syntactically simple, but semantically rather nontrivial


## Semantics: variety of definition approaches

$\pi$ : if $b$ then $x:=x+1$; else skip; $\mathbf{f i}$;
Even when a programming language is picked, a lot of approaches exist on how to define a semantics of a program

The most popular ones are:

- axiomatic approach:
- an assertion is a formula (of a special purely-logical language) which represents a set of data states
- a rule for a primitive statement is a set of pairs of assertions
- a rule for a complex statement says how pairs of assertions obtained for substatements are transformed into ones for the statement
- just like in Hoare logic, if we speak about while programs


## Operational semantics: big-step and small-step

$\pi$ : if $b$ then $x:=x+1$; else skip; fi;

The most popular and well-known variations of an operational approach to define program semantics are:

- natural (big-step) semantics
- each statement defines an input-output relation which says how the data is modified when the statement is fully executed
- for instance, "if the input for the statement $\pi$ is $\{b /$ true,$x / 2\}$, then the output is $\{b /$ true, $x / 3\}$ "
- structural (small-step) semantics
- each complex statement defines how the data is modified by the next most primitive execution step, and explicitly - what statement describes the rest of the execution
- for instance, "if the input for $\pi$ is $\{b /$ true,$x / 2\}$, and "to pick a branch" is a primitive execution step, then then next data state is still $\{b /$ true,$x / 2\}$, and the rest statement is $x:=x+1$;"


## Small-step semantics: state update

For a data state $\sigma$, a subscripted variable $x$ of a type $T$, and a value val of the same type $T, \sigma[x \leftarrow v a l]$ is a data state which differs from $\sigma$ as follows:

- if $x$ is a simple variable, then $\sigma[x \leftarrow v a l](x)=v a l$, and all other variables are mapped to the same values as by $\sigma$
- if $x$ is a subscripted variable (equals to $a\left[\varepsilon_{1}, \ldots, \varepsilon_{n}\right]$ for clarity), then
- $\sigma[x \leftarrow \operatorname{val}](a)\left(\sigma\left(\varepsilon_{1}\right), \ldots, \sigma\left(\varepsilon_{n}\right)\right)=$ val,
- images of all other arguments of the function $\sigma[x \leftarrow v a l]$ (a) equal to the corresponding images of $\sigma(a)$ (i.e. the rest of the array remains unchanged)
- all variables, except $a$, are mapped to the same values as by $\sigma$


## Small-step semantics of while programs

$\rightarrow_{\mathcal{I}}$ is a binary relation over $\Pi \times \Sigma$ which defines a small-step semantics of while programs operating in context of an interpretation $\mathcal{I}:\langle\pi, \sigma\rangle \rightarrow_{\mathcal{I}}\left\langle\pi^{\prime}, \sigma^{\prime}\right\rangle$ means that a primitive execution step of the statement $\pi$ on the input data $\sigma$ leads to the output data $\sigma^{\prime}$, and the "rest" statement is $\pi^{\prime}$

- $\langle x:=\varepsilon ;, \sigma\rangle \rightarrow_{\mathcal{I}}\langle s k i p ;, \sigma[x \leftarrow \mathcal{I} \llbracket \varepsilon \rrbracket(\sigma)]\rangle$
- if $\left\langle\pi_{1}, \sigma\right\rangle \rightarrow_{\mathcal{I}}\left\langle\pi_{1}^{\prime}, \sigma^{\prime}\right\rangle$, then $\left\langle\pi_{1} \pi_{2}, \sigma\right\rangle \rightarrow_{\mathcal{I}}\left\langle\pi_{1}^{\prime} \pi_{2}, \sigma^{\prime}\right\rangle$
- $\langle$ skip; $\pi, \sigma\rangle \rightarrow_{\mathcal{I}}\langle\pi, \sigma\rangle$
- if $\mathcal{I} \llbracket \varepsilon \rrbracket(\sigma)=$ true, then $\left\langle\right.$ if $\varepsilon$ then $\pi_{1}$ else $\left.\pi_{2} \mathbf{f i} ;, \sigma\right\rangle \rightarrow_{\mathcal{I}}\left\langle\pi_{1}, \sigma\right\rangle$, otherwise $\left\langle\right.$ if $\varepsilon$ then $\pi_{1}$ else $\pi_{2}$ fi; $\rangle \rightarrow_{\mathcal{I}}\left\langle\pi_{2}, \sigma\right\rangle$
- if $\mathcal{I} \llbracket \varepsilon \rrbracket(\sigma)=$ false, then $\langle$ while $\varepsilon$ do $\pi$ od;,$\sigma\rangle \rightarrow_{\mathcal{I}}\langle$ skip; , $\sigma\rangle$, otherwise $\langle$ while $\varepsilon$ do $\pi$ od; $\rangle \rightarrow_{\mathcal{I}}\langle\pi$ while $\varepsilon$ do $\pi$ od;,$\sigma\rangle$
$\left(\sigma_{i}, \sigma_{o}\right) \in \mathcal{I}(\pi)$ iff there exists a sequence of states

$$
\left\langle\pi, \sigma_{i}\right\rangle \rightarrow_{\mathcal{I}} \cdots \rightarrow_{\mathcal{I}}\left\langle\text { skip; }, \sigma_{o}\right\rangle
$$

## Small-step semantics: example

Let $\mathcal{I}$ be a typical interpretation, and $\pi$ : while $x<3$ do if $x>1$ then $x:=x+2$; else $x:=x+1$; fi; od;

Then

$$
\begin{aligned}
& \langle\pi,\{x / 2\}\rangle \rightarrow \mathcal{I} \\
& \langle\text { if } x>1 \text { then } x:=x+2 ; \text { else } x:=x+1 ; \text { fi; } \pi,\{x / 2\}\rangle \rightarrow_{\mathcal{I}} \\
& \langle x:=x+2 ; \pi,\{x / 2\}\rangle \rightarrow_{\mathcal{I}} \\
& \langle\text { skip; } \pi,\{x / 4\}\rangle \rightarrow_{\mathcal{I}} \\
& \langle\pi,\{x / 4\}\rangle \rightarrow \mathcal{I} \\
& \langle\text { skip; },\{x / 4\}\rangle
\end{aligned}
$$

Thus, $(\{x / 2\},\{x / 4\}) \in \mathcal{I}(\pi)$

## Other sequential programs

Now (at last!) we have mathematical means to describe any sequential program and its behavior:

- pick any programming language
- formalize a type system and type domains of the language
- write down syntactic rules of the language (all modern languages have those)
- carefully define semanitcs of all "static" components of the language, and then - its "dynamic" part: a small-step semantics


## But why do we need it?

(here go standard phrases about the critical importance of error-free programs, and about the rigorousness of mathematics)

Now the big question is:

## Proof systems

## How can we prove anything about the absence of program errors?

The question is much bigger than it seems:
Suppose someone gave you a random sequence of words similar to what is usually written in "Proof" sections of mathematical papers, and said
"done, this proves that the program is error-free" -
what means should you use to check mathematical consistency of a proof?

Exercise: take any (old enough) scientific paper on correctness of distributed algorithms, and find an implicit assumption or an inconsistency which makes the main result "not as complete and valid as it seemed to be" $\odot$

## Proof systems

## How can we prove anything about the absence of program errors?

One of the ways to lower the necessity of proof-checking is to formalize a proof as another mathematical object

Still, you need to prove that the mathematical definition of a proof is consistent (and introduce and solve several other problems), but once it is done, all well-formed formalized proofs become inherently proof-checked

The most famous collection of mathematical notions of a proof is known by many names, including:
proof systems, formal systems, deductive systems, and logical calculi

## Proof systems

A proof (recall: a random collection of words in a "Proof" section) contains a sequence of propositions, such as:

- (... thus,) the sequence $s$ is convergent. (...)
- (... by definition of a field and Lemma 5,) the ring $\mathcal{R}$ is a field. (Q.E.D.)
- (... assuming that $P \neq N P$,) the considered problem is hard(, which implies ...)

The first step to formalize a proof is to introduce a formal language of considered propositions

## Proof systems: formulae

A proof system starts with the notion of a formula:

- an alphabet is a set of symbols, and each formula is a finite sequence of these symbols
- syntactic rules define which sequences of symbols are formulae, and which are not
- typically, a collection of syntactic rules is a BNF
- intuitively, each formula corresponds to a certain proposition of a proof
- but the only strict meaning of a formula is the formula itself, if no additional definitions are provided

Several well-known examples of formulae:

- Boolean formulae: $x \& y \rightarrow z$
- first-order formulae: $\forall x(\exists y(x>y) \vee Q(x)) \rightarrow \exists x R(x)$
- temporal formulae: $\mathbf{G}($ request $\rightarrow \mathbf{F}$ response)
- Hoare triples: $\{x>y\} x:=x+y ;\{x<y\}$


## Proof systems: axioms

Some of the formulae correspond to propositions which require no proof (or proved a priori), for instance:

- addition is commutative: $\forall x \forall y(x+y=y+x)$
- a sequence is convergent iff <here goes the definition>:

$$
\forall s(\text { convergent }(s) \leftrightarrow \forall \varepsilon(\text { real }(\varepsilon) \& \varepsilon>0 \rightarrow \exists N(\ldots)))
$$

- every cow is an animal: $\forall c(\operatorname{cow}(c) \rightarrow$ animal $(c))$
- a program $\pi$ computes $(x+y)$ and stores it to $z$ :

$$
\left\{x=x_{0} \& y=y_{0}\right\} \pi\left\{z=x_{0}+y_{0}\right\}
$$

(if it is agreed to be okay to leave such a proposition unproved)

Such formulae are called axioms

## Proof systems: inference rules

A proof is usually not just "some random sequence" of propositions: the truth of each proposition "rationally" follows from the truth of previous propositions

An inference rule is a finite description of a relation between formulae: a tuple $\left(f_{1}, \ldots, f_{n}, f\right)$ is an element of the relation iff $f$ follows from $f_{1}, \ldots, f_{n}$ ("if propositions $f_{1}, \ldots, f_{n}$ are proved, then $f$ is also proved")

Inference rules are often (but not always) presented in the following form:


- $\varphi_{i}$ and $\varphi$ are formula schemata:
formulae, some parts of which are replaced by parameter names
- all tuples $\left(f_{1}, \ldots, f_{n}, f\right)$ of the corresponding relation are obtained from the schemata $\left(\varphi_{1}, \ldots, \varphi_{n}, \varphi\right)$ by replacement of parameter names with certain strings


## Proof systems: inference rules

Several examples of inference rules:

- modus ponens:
to prove $B$, it is sufficient to prove a) $A$, and b) that $A$ implies $B$

$$
\frac{A, A \rightarrow B}{B}
$$

- Small-step inference rules for while programs:

$$
\frac{\left\langle\pi_{1}, \sigma\right\rangle \rightarrow_{\mathcal{I}}\left\langle\pi_{1}^{\prime}, \sigma^{\prime}\right\rangle}{\left\langle\pi_{1} \pi_{2}, \sigma\right\rangle \rightarrow_{\mathcal{I}}\left\langle\pi_{1}^{\prime} \pi_{2}, \sigma^{\prime}\right\rangle}
$$

- Hoare inference rules: ...
- Any reliable rules you want to use:

$$
\frac{\operatorname{cow}(x)}{\operatorname{animal}(x)}
$$

## Proof system: derivation

Now we can tell how to formally prove anything
First of all,

- define the notion of a formula: say what propositions can be used in a proof
- define a set of axioms: say what propositions are absolutely true
- define a set of inference rules: say what proof methods are rational

A derivation is a sequence $f_{1}, f_{2}, \ldots, f_{k}$ of formulae such that for each $i, 1 \leq i \leq k$,

- either $f_{i}$ is an axiom
- or $\left(f_{j_{1}}, \ldots, f_{j_{n}}, f_{i}\right)$ is an element of a relation corresponding to any inference rule, and $j_{1}, \ldots, j_{n}<i$

A formula $f$ is provable iff there exists a derivation $f_{1}, \ldots, f_{k}$ such that $f_{k}=f$

## Hoare proof system

How can we prove anything about the absence of program errors?

A formula of a Hoare proof system (a Hoare triple) has the following form: $\{\varphi\} \pi\{\psi\}$, where $\varphi$ and $\psi$ are first-order formulae (which have a signature compliant with the signature of $\pi$ ), and $\pi$ is a program

Intuitively, the triple corresponds to the following proposition:

- partial correctness: for any input data state satisfying $\varphi$, if $\pi$ has an output data $\sigma$, then $\sigma$ satisfies $\psi$
- total correctness: for any input data state satisfying $\varphi, \pi$ has an output data $\sigma$, and $\sigma$ satisfies $\psi$


## Hoare proof system

Hoare axioms and inference rules for partial correctness of while programs in an interpretation $\mathcal{I}$ (recall all the courses in which Hoare logic was mentioned):
axioms: all first-order formulae valid in $\mathcal{I}$

$$
\text { axioms: }\{\varphi\} \text { skip; }\{\varphi\}
$$

$$
\begin{aligned}
\text { axioms: } & \{\varphi\{x / \varepsilon\}\} x:=\varepsilon ;\{\varphi\} \\
& \text { (the expression [term] } \varepsilon \\
& \text { should be "good enough") }
\end{aligned}
$$

$$
\begin{aligned}
& \text { rule: } \frac{\varphi \rightarrow \varphi^{\prime},\left\{\varphi^{\prime}\right\} \pi\left\{\psi^{\prime}\right\}, \psi^{\prime} \rightarrow \psi}{\{\varphi\} \pi\{\psi\}} \\
& \text { rule: } \frac{\{\varphi\} \pi_{1}\{\chi\},\{\chi\} \pi_{2}\{\psi\}}{\{\varphi\} \pi_{1} \pi_{2}\{\psi\}} \\
& \text { rule: } \frac{\{\varphi \& C\} \pi_{1}\{\psi\},\{\varphi \& \neg C\} \pi_{2}\{\psi\}}{\{\varphi\} \text { if } C \text { then } \pi_{1} \text { else } \pi_{2} \text { fi; }\{\psi\}} \\
& \text { rule: } \frac{\{\varphi \& C\} \pi\{\varphi\}}{\{\varphi\} \text { while } C \text { do } \pi \text { od; }\{\varphi \& \neg C\}}
\end{aligned}
$$

## Hoare proof system

Hoare axioms and inference rules
for total correctness of while programs in an interpretation $\mathcal{I}$
(that is something new):
axioms: all first-order formulae valid in $\mathcal{I}$

```
axioms: {\varphi} skip; {\varphi}
```

$$
\begin{aligned}
\text { axioms: } & \{\varphi\{x / \varepsilon\}\} \times:=\varepsilon ;\{\varphi\} \\
& \text { (the expression [term] } \varepsilon \\
& \text { should be "good enough") }
\end{aligned}
$$

$$
\text { rule: } \frac{\varphi \rightarrow \varphi^{\prime},\left\{\varphi^{\prime}\right\} \pi\left\{\psi^{\prime}\right\}, \psi^{\prime} \rightarrow \psi}{\{\varphi\} \pi\{\psi\}} \quad \text { rule: } \frac{\{\varphi\} \pi_{1}\{\chi\},\{\chi\} \pi_{2}\{\psi\}}{\{\varphi\} \pi_{1} \pi_{2}\{\psi\}}
$$

$$
\begin{aligned}
& \text { rule: } \frac{\{\varphi \& C\} \pi_{1}\{\psi\},\{\varphi \& \neg C\} \pi_{2}\{\psi\}}{\{\varphi\} \text { if } C \text { then } \pi_{1} \text { else } \pi_{2} \text { fi; }\{\psi\}} \\
& \text { rule: } \frac{\{\varphi \& C\} \pi\{\varphi\},\{\varphi \& C \& \varepsilon=z\} \pi\{\varepsilon<z\}, \varphi \rightarrow \varepsilon \geq 0}{\{\varphi\} \text { while } C \text { do } \pi \text { od; }\{\varphi \& \neg C\}}
\end{aligned}
$$

( $z$ is an integer variable not present in $\pi$ )

## Hoare proof system

Another big question is: do such proof systems actually work?

For instance,

- the following axiom schema breaks everything: $\{\varphi\} \pi\{\psi\}$
- the following inference rule breaks everything:

$$
\frac{\{\varphi\} \pi\{\psi\}}{\left\{\varphi^{\prime}\right\} \pi\left\{\psi^{\prime}\right\}}
$$

- the absence of any axiom or any inference rule breaks a lot

Provable formulae are defined syntactically, but we need semantics to check that what we formally prove is exactly what we intuitively want

## Proof systems: soundness and completeness

To measure the quality of a proof system (in general), all formulae are divided into valid and invalid: intuitively, a valid formula is a formula which corresponds to a true proposition

You probably know what is a validiy:

- "a first-order formula is valid in an interpretation $\mathcal{I}$ ": true for the meaning of constants defined by $\mathcal{I}$, and for all valuations of free variables
- "a Hoare triple is valid in an interpretation $\mathcal{I}$ ": this validity slightly differs in case of partial and total correctness proofs, and complies with the corresponding intuitive meaning


## Proof systems: soundness and completeness

A proof system (in general) is sound iff all provable formulae are valid
A proof system is complete iff all valid formulae are provable
Magically (by the results of a long research and a couple of heavy theorems), Hoare proof systems for partial and total correctness are both sound, and moreover,

- the system for partial correctness is complete
- if integer expressions are expressive enough (for instance, to represent all computable functions), then the system for total correctness is alse complete

Too good to be effectively true: the problem is hidden in the axioms, and in the (un)decidability

## That's all. Questions?

