

Complexity of Metric Temporal Logics with Counting and the Pnueli Modalities

Alexander Rabinovich

Sackler Faculty of Exact Sciences, Tel Aviv University, Israel 69978.

`rabinoa@post.tau.ac.il`

Abstract. The common metric temporal logics for continuous time were shown to be insufficient, when it was proved in [7, 12] that they cannot express a modality suggested by Pnueli. Moreover no temporal logic with a finite set of modalities can express all the natural generalizations of this modality. The temporal logic with counting modalities (*TLC*) is the extension of until-since temporal logic $TL(\mathbf{U}, \mathbf{S})$ by “counting modalities” $C_n(X)$ and \overline{C}_n ($n \in \mathbb{N}$); for each n the modality $C_n(X)$ says that X will be true at least at n points in the next unit of time, and its dual $\overline{C}_n(X)$ says that X has happened n times in the last unit of time. In [11] it was proved that this temporal logic is expressively complete for a natural decidable metric predicate logic. In particular the Pnueli modalities $Pn_k(X_1, \dots, X_k)$, “there is an increasing sequence t_1, \dots, t_k of points in the unit interval ahead such that X_i holds at t_i ”, are definable in *TLC*. In this paper we investigate the complexity of the satisfiability problem for *TLC* and show that the problem is PSPACE complete when the index of C_n is coded in unary, and EXPSPACE complete when the index is coded in binary. We also show that the satisfiability problem for the until-since temporal logic extended by Pnueli’s modalities is PSPACE complete.

1 Introduction

The temporal logic that is based on the two modalities “Since” and “Until” is popular among computer scientists as a framework for reasoning about a system evolving in time. By Kamp’s theorem [13] this logic has the same expressive power as the first order monadic logic of order, whether the system evolves in discrete steps or in continuous time. We will denote this logic by $TL(\mathbf{U}, \mathbf{S})$.

For systems evolving in discrete steps, this logic seem to supply all the expressive power needed. This is not the case for systems evolving in continuous time, as the logic cannot express metric properties like: “ X will happen within one unit of time”. The most straightforward extension which allows to express metric properties is to add modality which says that “ X will happen exactly after one unit of time”. Unfortunately, this logic is undecidable. Over the years different decidable extensions of $TL(\mathbf{U}, \mathbf{S})$ were suggested. Most extensively researched was *MITL* [2, 1, 5]. Other logics are described in [3, 14, 17, 6]. We introduced the language *QTL* (quantitative temporal logic) [8–10], which extends the

until-since temporal logic by two modalities: $\diamond_1 X$ and $\overleftarrow{\diamond}_1 X$. The formula $\diamond_1 X$ (respectively $\overleftarrow{\diamond}_1 X$) expresses that “ X will be true at some point during the next unit of time” (respectively, “ X was true at some point during the previous unit of time”). These extensions of $TL(\mathbf{U}, \mathbf{S})$ have the same expressive power, which indicates that they capture a natural fragment of what can be said about the system which evolve in time. These “first generation” metric extensions of $TL(\mathbf{U}, \mathbf{S})$ can be called *simple metric temporal logics*.

A. Pnueli was probably the first person to question if these simple logics are expressive enough for our needs. The conjecture that they cannot express the property “ X and then Y will both happen in the coming unit of time” is usually referred to as “Pnueli’s conjecture” [2, 17].

In [7, 12] we proved Pnueli’s conjecture, and we strengthened it significantly. To do this we defined for every natural k the “*Pnueli modality*” $Pn_k(X_1, \dots, X_k)$, which states that there is an increasing sequence t_1, \dots, t_k of points in the unit interval ahead such that X_i holds at t_i . We also defined the weaker “*Counting modalities*” $C_k(X)$ which state that X is true at least at k points in the unit interval ahead (so that $C_k(X) = Pn_k(X, \dots, X)$). To deal with the past we define also the dual past modality, $\overleftarrow{Pn}_k(X_1, \dots, X_k)$: there is a decreasing sequence t_1, \dots, t_k of points in the previous unit interval such that X_i holds at t_i , and $\overleftarrow{C}_k(X)$ which state that X was true at least at k points in the previous unit interval.

This yields a sequence of temporal logics TLP_n ($n \in \mathbb{N}$), where TLP_n is the standard temporal logic, with “Until” and “Since”, and with the addition of the k -place modalities Pn_k and \overleftarrow{Pn}_k for $k \leq n$. Similarly, TLC_n is the extension of $TL(\mathbf{U}, \mathbf{S})$ with the addition of modalities C_k and \overleftarrow{C}_k for $k \leq n$. We note also that TLP_1 is just the logic QTL and it represents the simple metric logics.

Let TLP be the union of TLP_n and TLC be the union of TLC_n .

We proved in [7, 12] that:

1. The sequence of temporal logics TLP_n is strictly increasing in expressive power. In particular, $C_{n+1}(X)$ is not expressible in TLP_n
2. TLP and TLC are decidable and have the same expressive power. Moreover they are expressively equivalent to a natural decidable fragment of first-order logic.

In this paper we investigate the complexity of the satisfiability problem for TLP and TLC . In [16] it was shown that $TL(\mathbf{U}, \mathbf{S})$ is PSPACE complete. In [7, 10] we provided a polynomial satisfiability preserving translation from QTL to $TL(\mathbf{U}, \mathbf{S})$ and derived PSPACE completeness of QTL .

In this paper we first prove that the satisfiability problem for TLP is PSPACE complete.

When one write a TLC formula there are two natural possibility: to write index n of C_n in unary or in binary. We show that the satisfiability problem for TLC is PSPACE complete when the index of C_n is coded in unary, and EXSPACE complete when the index is coded in binary.

Our results holds both when the interpretation of temporal variable is arbitrary and when we assume that they satisfy the finite variability assumption (FVA) which states that no variable changes its truth-value infinitely many times in any bounded interval.

In [12] we proved that there is no temporal logic L with finitely many modalities definable in the monadic second-order logic expanded by $+1$ function such that over the reals L is at least as expressive as TLC . Our conjecture was that this result can be extended to the non-negative reals. Our proofs refute this conjecture.

The paper is divided as follows: In Sect. 2, we recall definitions and previous results. In Sect. 3, we prove PSPACE completeness for TLP and as a consequence obtain PSPACE completeness for TLC under the unary coding of indexes. In Sect. 4, EXPSPACE completeness for TLC under the binary coding of indexes is proved. Section 5 contains additional complexity results and a discussion on the expressive power of TLC .

2 Preliminaries

First, we recall the syntax and semantics of temporal logics and how temporal modalities are defined using truth tables, with notations adopted from [4, 9].

Temporal logics use logical constructs called “modalities” to create a language that is free from quantifiers.

The syntax of a *Temporal Logic* has in its vocabulary a countably infinite set of *propositions* $\{X_1, X_2, \dots\}$ and a possibly infinite set $B = \{O_1^{l_1}, O_2^{l_2}, \dots\}$ of *modality names* (sometimes called “temporal connectives” or “temporal operators”) with prescribed arity indicated as superscript (we usually omit the arity notation). $TL(B)$ denotes the *temporal logic based on modality-set* B (and B is called the *basis* of $TL(B)$). Temporal formulae are built by combining atoms (the propositions X_i) and other formulae using Boolean connectives and modalities (with prescribed arity). Formally, the syntax of $TL(B)$ is given by the following grammar:

$$\phi ::= X_i \mid \phi_1 \wedge \phi_2 \mid \phi_1 \vee \phi_2 \mid \phi_1 \leftrightarrow \phi_2 \mid \neg\phi_1 \mid O_i(\phi_1, \phi_2, \dots, \phi_{l_i})$$

We will use (in our metalanguage) S, X, Y, Z to range over variables.

A *structure for Temporal Logic*, in this work, is the non negative real line with monadic predicates $\mathcal{M} = \langle \mathbb{R}^+, <, S_1, S_2, \dots \rangle$, where the predicate S_i are the interpretation in \mathcal{M} of the variable S_i . (All our complexity results can be easily adopted to the models over the whole real line \mathbb{R} .) Every modality $O^{(k)}$ is interpreted in the structure \mathcal{M} as an operator $O_{\mathcal{M}}^{(k)} : [\mathbb{P}(\mathbb{R}^+)]^k \rightarrow \mathbb{P}(\mathbb{R}^+)$ which assigns “the set of points where $O^{(k)}[A_1, \dots, A_k]$ holds” to the k -tuple $\langle A_1, \dots, A_k \rangle \in \mathbb{P}(\mathbb{R}^+)^k$. ($\mathbb{P}(\mathbb{R}^+)$ denotes the set of all subsets of \mathbb{R}^+). Once every modality corresponds to an operator the semantics is defined by structural induction:

- for atomic formulas: $\mathcal{M}, t \models S$ iff $t \in S$.

- for Boolean combinations the definition is the usual one.
- for $O^{(k)}(\varphi_1, \dots, \varphi_k)$

$$\mathcal{M}, t \models O^{(k)}(\varphi_1, \dots, \varphi_k) \quad \text{iff} \quad t \in O_{\mathcal{M}}^{(k)}(A_{\varphi_1}, \dots, A_{\varphi_k})$$

where $A_{\varphi} = \{ \tau : \mathcal{M}, \tau \models \varphi \}$

For the modality to be of interest the operator $O^{(k)}$ should reflect some intended connection between the sets A_{φ_i} of points satisfying φ_i and the set of points $O[A_{\varphi_1}, \dots, A_{\varphi_k}]$. The intended meaning is usually given by a formula in an appropriate predicate logic:

Truth Tables: A formula $\overline{O}(t, X_1, \dots, X_k)$ in the predicate logic L is a *Truth Table* for the modality $O^{(k)}$ if for every structure \mathcal{M}

$$O_{\mathcal{M}}(A_1, \dots, A_k) = \{ \tau : \mathcal{M} \models \overline{O}[\tau, A_1, \dots, A_k] \} .$$

2.1 Since-Until Temporal Logic

The modalities *until* and *since* are most commonly used in temporal logic for computer science. They are defined through the following truth tables:

- The modality $XU Y$, “ X until Y ”, is defined by

$$\psi(t_0, X, Y) \equiv \exists t_1(t_0 < t_1 \wedge Y(t_1) \wedge \forall t(t_0 < t < t_1 \rightarrow X(t))) .$$

- The modality $XS Y$, “ X since Y ”, is defined by

$$\psi(t_0, X, Y) \equiv \exists t_1(t_0 > t_1 \wedge Y(t_1) \wedge \forall t(t_1 < t < t_0 \rightarrow X(t))) .$$

Reynolds [16] proved

Theorem 2.1 *The satisfiability problem for $TL(\mathbf{U}, \mathbf{S})$ over the reals is PSPACE complete.*

We will use standard abbreviations. E.g., $\diamond X$ - sometimes in the future X holds - abbreviates $True\mathbf{U}X$; $\square X$ - always in the future X holds - abbreviates $\neg(True\mathbf{U}\neg X)$; the past modalities $\overleftarrow{\diamond} X$ - “ X happened in the past”, and $\overleftarrow{\square} X$ - “ X have been always true”, are defined similarly. The modality *always* acts like the universal quantifier and is defined as

$$always(X) : \quad \overleftarrow{\square} X \wedge X \wedge \square X .$$

$Llim(X)$ and $Rlim(X)$ abbreviate the formulas

$$Llim(X) : \quad \neg(\neg X\mathbf{S}True)$$

$$Rlim(X) : \quad \neg(\neg X\mathbf{U}True)$$

$Llim(X)$ holds at t if t is a left limit of X , i.e., for every $t_1 < t$ there is an X in the interval (t_1, t) . $Rlim(X)$ holds at t if t is a right limit of X .

2.2 Three Metric Temporal Logics

We recall the definitions of three temporal logics: Quantitative Temporal Logic - QTL , Temporal Logic with Counting - TLC and Temporal Logic with Pnueli's modalities - TLP .

The logic QTL in addition to modalities \mathbf{U} and \mathbf{S} has two modalities $\diamond_1 X$ and $\overleftarrow{\diamond}_1 X$. These modalities are defined by the tables with free variable t_0 :

$$\begin{aligned}\diamond_1 X &: \quad \exists t((t_0 < t < t_0 + 1) \wedge X(t)) \\ \overleftarrow{\diamond}_1 X &: \quad \exists t((t - 1 < t < t_0) \wedge X(t))\end{aligned}$$

In [7] it was proved

Theorem 2.2 *The satisfiability problem for QTL is PSPACE complete.*

The logic TLP is the extension of $TL(\mathbf{U}, \mathbf{S})$ by an infinite set of modalities $Pn_k(X_1, \dots, X_k)$ and $\overleftarrow{Pn}_k(X_1, \dots, X_k)$. These modalities are defined by the tables with free variable t_0 :

$$\begin{aligned}Pn_k(X_1, \dots, X_k) &: \quad \exists t_1 \dots \exists t_k (t_0 < t_1 < \dots < t_k < t_0 + 1 \wedge \bigwedge_{i=1}^k X_i(t_i)) \\ \overleftarrow{Pn}_k(X_1, \dots, X_k) &: \quad \exists t_1 \dots \exists t_k (t_0 - 1 < t_1 < \dots < t_k < t_0 \wedge \bigwedge_{i=1}^k X_i(t_i))\end{aligned}$$

Finally, the logic TLC - the temporal logic with counting modalities - is the extension of $TL(\mathbf{U}, \mathbf{S})$ by an infinite set of modalities $C_k(X)$ and $\overleftarrow{C}_k(X)$. These modalities are defined by the tables with free variable t_0 :

$$\begin{aligned}C_k(X) &: \quad \exists t_1 \dots \exists t_k (t_0 < t_1 < \dots < t_k < t_0 + 1 \wedge \bigwedge_{i=1}^k X(t_i)) \\ \overleftarrow{C}_k(X) &: \quad \exists t_1 \dots \exists t_k (t_0 - 1 < t_1 < \dots < t_k < t_0 \wedge \bigwedge_{i=1}^k X(t_i))\end{aligned}$$

We recall the terminology that is used when comparing the expressive power of languages.

Let \mathcal{C} be a class of structures and let L and L' be temporal logics.

1. L is *at least as expressive as* L' over a class \mathcal{C} if for every formula φ of L' there is a formula ψ in L such that for every structure \mathcal{M} in \mathcal{C} and for every $\tau \in \mathcal{M}$: $\mathcal{M}, \tau \models \varphi$ iff $\mathcal{M}, \tau \models \psi$.
2. L and L' are *expressively equivalent* over \mathcal{C} if L is at least as expressive as L' over \mathcal{C} and L' is at least as expressive as L over \mathcal{C} .

We deal here with the temporal logics over the class of non-negative real numbers. We will say “ L is *at least as expressive as* (respectively, is expressively equivalent to) L' if L is *at least as expressive as* (respectively, is expressively equivalent to) L' over this class.

The following theorem from [12] compares the expressive power of TLP , TLC and QTL .

Theorem 2.3 (Comparing the Expressive Power) *TLP and TLC are expressively equivalent. TLP and TLC are strictly more expressive than QTL .*

2.3 Size of Formulas

Usually the *size* of a formula is defined as its length (string representation) or the size of its directed acyclic graph representation (DAG). The logics TLC and TLP have infinite sets of modalities and therefore we have to agree how to code the names of modalities. There are two natural possibilities: to write index k of C_k and Pn_k in unary or in binary. For TLP formulas this decision affects the size of the formulas up to a constant factor, and, therefore, it is not important. For TLC formulas the binary coding might be exponentially shorter than the unary coding. Our main results show that the satisfiability problem for TLC is PSPACE complete when the index of C_k is coded in unary, and EXPSPACE complete when the index is coded in binary.

Note that there might be an exponential gap in the size of a DAG representation of a formula and its length. Our proofs of upper bounds will be given for DAG representation (and hence the bounds are valid for string representations). Our proofs of lower bounds will be given for string representations (and hence the bounds are valid for DAG representation).

3 TLP is PSPACE Complete

Theorem 3.1 *The satisfiability problem for TLP is PSPACE complete.*

The PSPACE hardness immediately follows from PSPACE hardness for the satisfiability problem for $TL(\mathbf{U}, \mathbf{S})$ which is a subset of TLP . Below we prove that the satisfiability problem is in PSPACE.

A structure \mathcal{M} is called *proper* if it is an expansion of $\langle \mathbb{R}^+, <, \mathbb{N}, Even, Odd \rangle$ by unary predicates. Here \mathbb{N} , *Even*, and *Odd* are the sets of natural, even and odd numbers; these sets will be denoted by predicate names N , E , O .

In contrast to the fact that TLP is much more expressive than QTL over the class of all real structures and over the class of finite variability structures [7, 9], we are going to show that they are expressively equivalent over the class of proper structures. Moreover, there is a polynomial meaning preserving (over the proper structures) translation from TLP to QTL .

Lemma 3.2 *1. For every k there is a QTL formula $\Psi_k(X_1, \dots, X_k, N, E, O)$ which is equivalent over the proper structures to $Pn_k(X_1, \dots, X_k)$. Furthermore, the size of Ψ_k is less than $100k^2$.*

2. For every k there is a QTL formula $\overleftarrow{\Psi}_k(X_1, \dots, X_k, N, E, O)$ which is equivalent over the proper structures to $\overleftarrow{Pn}_k(X_1, \dots, X_k)$. Furthermore, the size of Ψ_k is less than $100k^2$.

Proof. (1) For $i \leq j \leq k$ define formulas $\phi_{i,j}$ as follows:

$$\phi_{i,i} := (\neg N)\mathbf{U}X_i$$

$$\phi_{i,i+l+1} := (\neg N)\mathbf{U}(X_i \wedge \neg N \wedge \phi_{i+1,i+l+1})$$

It is clear that the size of $\phi_{i,j}$ is less than $10(j - i + 1)$ and that $\phi_{i,j}$ holds at t iff there are $t < t_i < t_{i+1} < \dots < t_j \leq n$, where n is the smallest integer greater than t , such that $\bigwedge_{l=i}^j X_l(t_l)$. Similarly, there are formulas $\overleftarrow{\phi}_{i,j}$ such that $\overleftarrow{\phi}_{i,j}$ holds at t iff there are $t > t_j > \dots > t_i > n$, where n is the largest integer less than t , and $\bigwedge_{l=i}^j X_l(t_l)$ holds.

The formula Ψ_k which is equivalent to Pn_k over the proper structures can be defined as the disjunction of the following formulas:

1. $\phi_{1,k}$ - “ $\phi_{1,k}$ holds at t if there are $t < t_1 < t_2 < \dots < t_k \leq n$, where n is the smallest integer greater than t , such that $\bigwedge_{l=1}^k X_l(t_l)$ ”.
2. $\bigvee_{n=1}^{k-1} (\neg N)\mathbf{U}E \wedge \phi_{1,n} \wedge \diamond_1((\neg N)\mathbf{S}E \wedge \overleftarrow{\phi}_{n+1,k})$ - this covers the case when t is in an interval $[2m - 1, 2m]$ for some integer m . The n -th disjunct says that $\bigwedge_{l=1}^n X_l(t_l)$ holds for $t < t_1 < \dots < t_n \leq 2m$ and in the interval $(2m, 2m + 1)$ there are $t_{n+1} < \dots < t_k < t + 1$ such that $\bigwedge_{l=n+1}^k X_l(t_l)$ holds.
3. $\bigvee_{n=1}^{k-1} (\neg N)\mathbf{U}O \wedge \phi_{1,n} \wedge \diamond_1((\neg N)\mathbf{S}O \wedge \overleftarrow{\phi}_{n+1,k})$ - this is similar to the previous disjunct, but deals with t in the intervals $[2m, 2m + 1]$, where m is an integer.

This proves (1). The proof of (2) is similar. \square

Corollary 3.3 *TLP and QTL are expressively equivalent over the class of proper structures. Furthermore, for every TLP formula φ there is a QTL formula ψ which is equivalent to φ over the proper structures and $|\psi|$ is $O(|\varphi|^2)$.*

Proof. We define a meaning preserving translation Tr from TLP to QTL.

1. For variables $Tr(X) := X$.
2. If op is a Boolean connective $Tr(\varphi_1 op \varphi_2) := Tr(\varphi_1) op Tr(\varphi_2)$.
3. For until and since modalities $Tr(\varphi_1 \mathbf{U} \varphi_2) := (Tr(\varphi_1))\mathbf{U}(Tr(\varphi_2))$, and $Tr(\varphi_1 \mathbf{S} \varphi_2) := (Tr(\varphi_1))\mathbf{S}(Tr(\varphi_2))$.
4. $Tr(Pn_k(\varphi_1, \dots, \varphi_k))$ is obtained by substitution of $Tr(\varphi_i)$ instead of X_i in Ψ_k ; Similarly, $Tr(\overleftarrow{Pn}_k(\varphi_1, \dots, \varphi_k))$ is obtained by substitution of $Tr(\varphi_i)$ instead of X_i in $\overleftarrow{\Psi}_k$.

It is clear that φ is equivalent to $Tr(\varphi)$ over the proper structures. In Ψ_k and in $\overleftarrow{\Psi}_k$ every variable appears at most k times, therefore the size (of the DAG representation) of $Tr(\varphi)$ is $O(|\varphi|^2)$. \square

The next lemma shows that the set of proper structures is definable by a *QTL* formula.

Lemma 3.4 *There is a QTL formula $PROPER(Y, Z, U)$ such that $\mathbb{R}^+, t \models PROPER(N, E, O)$ iff N is the set of natural numbers, and E and O are the sets of even and odd numbers.*

Proof. (1) Let $Nat(Y)$ be the conjunction of the following formulas:

1. $\overline{\square} False \rightarrow Y$ - “ Y holds at zero”.
2. $always(Y \rightarrow \square_1 \neg Y)$ - “If Y holds at t then $\neg Y$ holds at all points in $(t, t+1)$ ”.
3. $always(\neg Y \rightarrow \diamond_1 Y)$ - “If Y does not hold at t then Y holds at some point in $(t, t+1)$ ”.

It is clear that the set of naturals is unique set that satisfies $Nat(Y)$.

(2) Let $EVEN(Y, Z)$ be the conjunction of

1. $Nat(Y)$ - “ Y is the set of the natural numbers”
2. $always(Z \rightarrow Y)$ - “ Z is a subset of the natural numbers”.
3. $\overline{\square} False \rightarrow Z$ - “ Z holds at zero”.
4. $always(Z \rightarrow (\neg Y)U(Y \wedge \neg Z))$ - “if Z holds at a natural number n then it does not hold at the next natural number”.
5. $always(\neg Z \wedge Y \rightarrow (\neg Y)U(Y \wedge Z))$ - “if Z does not hold at a natural number n then it holds at the next natural number”.

It is clear that $EVEN(N, E)$ holds iff N is the set of naturals and E is the set even numbers.

$PROPER(Y, Z, U)$ can be defined as $EVEN(Y, Z) \wedge always(U \leftrightarrow (Y \wedge \neg Z))$. □

Finally, to complete the proof of Theorem 3.1, observe that a *TLP* formula φ is satisfiable iff φ is satisfiable over a proper structure iff $PROPER(N, E, O) \wedge \varphi$ is satisfiable iff the *QTL* formula $PROPER(N, E, O) \wedge \psi$ is satisfiable, where ψ is constructed as in Corollary 3.3. Since, the satisfiability problem for *QTL* is in PSPACE we obtain that the satisfiability problem for *TLP* is in PSPACE and this completes the proof of Theorem 3.1.

As a consequence we obtain the following corollary.

Corollary 3.5 *The satisfiability problem for TLC is PSPACE complete under the unary coding.*

Proof. Note that $C_k(X)$ is equivalent to $Pn_k(X, X, \dots, X)$. The translation from *TLC* to *TLP* based on this equivalence is linear in the size of DAG representation. Hence, by Theorem 3.1, *TLC* is in PSPACE.

The PSPACE hardness immediately follows from PSPACE hardness for the satisfiability problem for $TL(\mathbf{U}, \mathbf{S})$ which is a subset of *TLC*. □

4 EXPSPACE Completeness for *TLC*

Theorem 4.1 *The satisfiability problem for TLC is EXPSPACE complete under the binary coding.*

The upper bound immediately follows from Corollary 3.5. Below we prove that the satisfiability problem is EXPSPACE hard. For every Turing Machine M which works in space 2^n and every input x of length n we construct a *TLC* formula $Acc_{M,x}$ which is satisfiable iff M accepts x . Moreover $Acc_{M,x}$ is computable from M and x in polynomial time. This proves EXPSPACE hardness with respect to the polynomial reductions.

A one-tape deterministic Turing machine M is $(Q, q_0, q_{acc}, q_{rej}, \Gamma, b, \nu)$, where Q is the set of states, $q_0, q_{acc}, q_{rej} \in Q$ are initial, accepting and rejecting states, Γ is the alphabet, $b \in \Gamma$ is the blank symbol and $\nu : ((Q \setminus \{q_{acc}, q_{rej}\}) \times \Gamma) \rightarrow (Q \times \Gamma \times \{-1, 0, 1\})$ is the transition function. If the head is over a symbol σ and M is in a state q and $\nu(q, \sigma) = \langle q', \sigma', d \rangle$, then M replace σ by σ' changes its state to q' and moves d cells to the right (if $d = -1$ then it moves one cell left). There is no transition from the accepting and rejecting states.

A configuration (or an instantaneous description) is a member of $\Gamma^*Q\Gamma^+$ and represents a complete state of the Turing machine.

Let $\alpha = xq\sigma y$ be a configuration, where $\sigma \in \Gamma$, $x, y \in \Gamma^*$ and $q \in Q$. We define $tape(\alpha) = x\sigma y$, and $state(\alpha) = q$. It describes that for $i \leq |tape(\alpha)|$, the i -th cell of the tape contains the i -th symbol of $tape(\alpha)$ and all other cells contain blank; the control state is q and the head is over the symbol σ at the position $|x| + 1$.

We deal with Turing machines which use at most 2^n tape cells on inputs of length n . A configuration α is an n -configuration if $tape(\alpha)$ has 2^n symbols. Hence, a computation of M on an input $x = x_1 \dots x_n$ of length n can be described by a sequence $\alpha_1 \alpha_2 \dots$ of n -configurations, where $\alpha_1 = q_0 x_1 x_2 \dots x_n b^{2^n - n}$ is the initial n -configuration for the input x .

For n -configurations α and β we write $\alpha \rightarrow_M \beta$ if β is obtained from α according to the transition function of M . Whenever M is clear from the context we will write $\alpha \rightarrow \beta$. Note that if $\alpha \rightarrow \beta$ then $tape(\alpha)$ and $tape(\beta)$ have the same length.

A *computation sequence* is a sequence of configurations $\alpha_1 \dots \alpha_k$ for which $\alpha_i \rightarrow \alpha_{i+1}$, $1 \leq i < k$. A configuration β is *reachable* from a configuration α if there exists a computation sequence $\alpha_1 \dots \alpha_k$ with $\alpha = \alpha_1$ and $\beta = \alpha_k$.

Acceptance conditions. A configuration α is an accepting (respectively, rejecting) configuration if $state(\alpha)$ is accepting (respectively, rejecting) state. A computation sequence $\alpha_1 \dots \alpha_m$ is accepting (respectively, rejecting) if α_m is accepting (respectively, rejecting).

We are going to encode computations of M over proper structures, i.e., over expansions of $\langle \mathbb{R}^+, <, \mathbb{N}, Even, Odd \rangle$ by monadic predicates. All these predicates will have finite variability and the EXPSPACE lower bound holds both under the finite variability and arbitrary interpretations. We will denote by \mathcal{M} an expansion of $\langle \mathbb{R}^+, <, \mathbb{N} \rangle$ by unary predicates.

From now on we fix a Turing machine M with the alphabet $\{0, 1, b\}$ of space complexity $\leq 2^n$. W.l.o.g. we assume that M never moves to the left of the first input cell. All definitions and constructions below will be for this M .

Let $\alpha_1, \dots, \alpha_k$ be a sequence of n -configurations (not necessary a computation sequence). The i -th configuration α_i will be encoded on the interval $(i-1, i)$ with integer end-points as follows: The interval will contain 2^n points $\tau_{i,j}$ such that $i-1 < \tau_{i,1} < \tau_{i,2} < \dots < \tau_{i,2^n} < i$ and the predicate T will hold exactly at these points in the interval. All other predicates described below will be subsets of T . A_0, A_1 and A_b will partition T ; $\tau_{i,j}$ will be in A_0 (respectively, in A_1 or in A_b) if the j -th tape symbol of α_i is 0 (respectively 1, or blank). Predicates S_q for $q \in Q$ are interpreted in $(i-1, i)$ as follows: $\tau_{i,j} \in S_q$ if q is the state of α_i and the head is over the j -th tape symbol.

Definition 4.2 *Let \mathcal{M} be an expansion of $\langle \mathbb{R}^+, <, \mathbb{N} \rangle$ by predicates T, A_0, A_1, A_b, S_q for $q \in Q$. For $i \in \mathbb{N}$, we say that the interval $[i, i+1]$ of \mathcal{M} represents a legal n -configuration if*

1. *it contain 2^n points in T and all these points are inside $(i, i+1)$.*
2. *A_0, A_1 and A_b partition T .*
3. *$\cup_{q \in Q} S_q \subseteq T$ and there is exactly one $q \in Q$ such that $S_q \cap [i, i+1]$ is a singleton and for all $q' \neq q$, the set $S_{q'} \cap [i, i+1]$ is empty.*

The following lemma is easy. We use there \vec{S} for the tuple of predicate names $\langle S_q : q \in Q \rangle$.

Lemma 4.3 *1. There is a TLC formula $\varphi_0(N, T, A_0, A_1, A_b, \vec{S})$ which holds in a structure \mathcal{M} iff there is $l \in \mathbb{N}$ such that for every $i < l$ the interval $[i, i+1]$ represents a legal n -configuration, the configuration represented in the interval $[l-1, l]$ is accepting or rejecting, and no $\tau \geq l$ is in $T \cup A_0 \cup A_1 \cup A_b \cup \cup_{q \in Q} S_q$. Furthermore, the size of φ_0 is $O(n)$.*

2. For every $x = x_1 \dots x_n \in \{0, 1\}^n$, there is a formula $INIT_x$ which holds in a structure \mathcal{M} iff the interval $[0, 1]$ represents the initial n -configuration σ_0 with input x . Furthermore, the size of $INIT_x$ is $O(n)$.

Our next task is to specify that the configuration represented in an interval $[i, i+1]$ is obtained from the configuration represented in $[i-1, i]$ according to the transition function of M . We have to express (1) the head is moved properly and update the symbols under the head correctly and (2) all other symbols are unchanged.

The next lemma shows that the cells numbered from 1 to 2^n can be succinctly described by their binary representations.

Lemma 4.4 *There is a formula $\varphi_1(N, T, B_1, \dots, B_n)$ such that if for every $i \in \mathbb{N}$ the interval $(i, i+1)$ contains at most 2^n points from T then $\mathcal{M}, 0 \models \varphi_1$ iff for every $i \in \mathbb{N}$ and $\tau \in (i, i+1)$: if τ is the j -th occurrence of T in this interval then $\tau \in B_l$ iff the l -th bit of the binary representation of $j-1$ is one. Furthermore, the size of φ_1 is $O(n^2)$.*

Proof. φ_1 is *always*(ψ_1), where ψ_1 is the conjunction of

1. $\bigvee B_l \rightarrow (T \wedge \neg N) - B_l$ are subsets of $T \setminus \mathbb{N}$.
2. $N \wedge (\neg N) \mathbf{U}(T \wedge \neg N) \rightarrow ((\neg N) \mathbf{U}(T \wedge \bigwedge_{l=1}^n \neg B_l))$ - the first occurrence of T in $(i, i+1)$ has binary representation $00\dots 0$, i.e., is not in $\cup B_l$.
3. $T \wedge \neg N \wedge (\neg N) \mathbf{U}(T \wedge \neg N) \rightarrow \bigvee_k \gamma_k$, where γ_k is

$$(\neg B_k \wedge \bigwedge_{m=k+1}^n B_m) \rightarrow ((\neg T) \mathbf{U}(T \wedge (B_k \wedge \bigwedge_{m=k+1}^n \neg B_m) \wedge \bigwedge_{m=1}^{k-1} (B_m \rightarrow (\neg T) \mathbf{U}(T \wedge B_m))))$$

The formula expresses that if τ is not the last occurrence of T in $(i, i+1)$ and its binary code has 0 at k -th place and 1 at places $k+1, \dots, n$ then the code of the next occurrence of T has 1 at k -th place and zero at places $k+1, \dots, m$ and both occurrences have the same bit in the binary code at places $1, \dots, k-1$. \square

Now we can express that the head moves properly, state is updated correctly and the type symbol under the head is updated correctly.

Lemma 4.5 *There is a formula φ_2 such that if \mathcal{M} represents a terminating sequence of configurations $\alpha_1, \dots, \alpha_l$ and $\mathcal{M}, 0 \models \varphi_1$, then¹ $\mathcal{M}, 0 \models \varphi_2$ iff*

for every $i < l$ if in α_i the head is over symbol σ at position j and the state is q and $\nu(q, \sigma) = \langle q'.\sigma', d \rangle$ then the state in the α_{i+1} is q' the head is at the position $j+d$, the symbol at position j is σ' .

Furthermore, the size of φ_2 is $O(n^2)$.

Proof. Let $\nu(q, \sigma) = \langle q'.\sigma', 1 \rangle$ and let $S := \bigvee_{q_1 \in Q} S_{q_1}$
Let $\psi_{q,\sigma}$ be the conjunction of

1. the heads moved one position to the right: $S_q \wedge A_\sigma \rightarrow \bigvee_{k=1}^n \gamma'_k$ where γ'_k is obtained from γ_k after substitution of S instead T (see proof of Lemma 4.4).
2. The state and the symbols under the head were updated correctly: $S_q \wedge A_\sigma \rightarrow (\neg \bigvee_{q_1 \in Q} S_{q_1}) \mathbf{U}(S_{q'} \wedge (\neg T) \mathbf{S}A_{\sigma'})$

When $\nu(q, \sigma) = \langle q'.\sigma', 0 \rangle$ and $\nu(q, \sigma) = \langle q'.\sigma', -1 \rangle$ the formula $\psi_{q,\sigma}$ is defined similarly.

The desirable formula φ_2 can be defined as *always*($\bigwedge_{q \notin \{q_a, q_r\}} \bigwedge_{\sigma} \psi_{q,\sigma}$). \square

The creative part of our proof is to show how to express succinctly that the symbols not under the head are unchanged. In order to do this we introduce the following notion.

Assume that \mathcal{M} represent a terminating sequence of configuration $\alpha_1, \dots, \alpha_l$. Recall that $\tau_{i,j} \in \mathbb{R}^+$ is the j -th occurrence of T in the interval $(i-1, i)$. We

¹ Until the end of this section φ_1 is the formula from Lemma 4.3. The scope of the definition of φ_2 from this lemma and formulas φ_3 and φ_4 from the following lemmas extends to the end of this section.

denote by $\text{tape}(\alpha_i)[j]$ the j -th symbol of $\text{tape}(\alpha_i)$. We say that \mathcal{M} is *well-timed* if for all $i < l$ and $j \leq 2^n$ and some positive $\epsilon_{i,j}$, $\delta_{i,j}$:

$$\tau_{i+1,j} = \begin{cases} 1 + \tau_{i,j} + \epsilon_{i,j} & \text{if } \text{tape}(\alpha_i)[j] \text{ is } 0 \\ 1 + \tau_{i,j} - \delta_{i,j} & \text{if } \text{tape}(\alpha_i)[j] \text{ is } 1 \\ 1 + \tau_{i,j} & \text{if } \text{tape}(\alpha_i)[j] \text{ is blank} \end{cases} \quad (\text{Eq. } WT)$$

First observe

Lemma 4.6 *if $\alpha_1 \dots \alpha_l$, is a terminating sequence of n -configuration, then there is a well-timed \mathcal{M} which represents this sequence.*

Proof. Just choose $\tau_{1,j}$ as $\frac{j}{2^{n+1}}$ (for $j = 1, \dots, 2^n$) and choose $\epsilon_{i,j} = \delta_{i,j}$ as $\frac{1}{3l \times (2^{n+1})}$. Define $\tau_{i+1,j}$ as in Eq. WT. Our choice of $\epsilon_{i,j}$, $\delta_{i,j}$ ensures that $i-1 < \tau_{i,1} < \tau_{i,2} < \dots < \tau_{i,2^n} < i$ for all $i \leq l$. \square

Lemma 4.7 *There is a formula φ_3 such that $\mathcal{M} \models \varphi_3$ iff \mathcal{M} is a well-timed sequence of n -configurations. Furthermore, the size of φ_3 is $O(n)$.*

Proof. Let ψ be the conjunction of the following formulas

1. $A_b \rightarrow (C_{2^n-1}(T) \wedge Llim(C_{2^n-1}(T)) \wedge Rlim(C_{2^n-1}(T)))$
2. $A_1 \rightarrow (C_{2^n}(T) \wedge Llim(C_{2^n+1}(T)) \wedge Rlim(C_{2^n}(T)))$
3. $A_0 \rightarrow (C_{2^n-1}(T) \wedge Llim(C_{2^n}(T)) \wedge Rlim(C_{2^n-1}(T)))$

(Recall that $Llim(X)$ (respectively, $Rlim(X)$) holds at t iff t is a left limit (respectively, a right limit of X), see Sect. 2.2)

Let \mathcal{M}' represents an n -configuration α_i in $[i, i+1]$ and has 2^n occurrences of T in $[i+1, i+2]$ all the occurrences inside $(i+1, i+2)$. The crucial observation is that Eq. WT holds iff $\mathcal{M}', \tau \models \psi$ for every $\tau \in [i, i+1]$.

From ψ it is easy to construct φ_3 . Just express that φ_0 holds, and ψ holds at all points except the points of the interval where the last configuration is represented. \square

We are now ready to specify that if a symbols is not under the head then in the next configuration it will be unchanged.

Lemma 4.8 *There is a formula φ_4 such that if \mathcal{M} represents a well-timed terminating sequence of n -configurations $\alpha_1, \dots, \alpha_l$ and $\mathcal{M}, 0 \models \varphi_1$, then $\mathcal{M}, 0 \models \varphi_4$ iff*

for every $i < l$ if in α_i the head is at position j , then $\text{tape}(\alpha_i)[m] = \text{tape}(\alpha_{i+1})[m]$ for every $m \neq j$.

Furthermore, the size of φ_4 is $O(n)$.

Proof. Let ψ be the conjunction of the following formulas

1. $A_b \rightarrow (\overleftarrow{C}_{2^n-1}(T) \wedge Llim(\overleftarrow{C}_{2^n-1}(T)) \wedge Rlim(\overleftarrow{C}_{2^n-1}(T)))$

2. $A_1 \rightarrow (\overleftarrow{C}_{2^n}(T) \wedge Rlim(\overleftarrow{C}_{2^{n+1}}(T)) \wedge Llim(\overleftarrow{C}_{2^n}(T)))$
3. $A_0 \rightarrow (\overleftarrow{C}_{2^{n-1}}(T) \wedge Rlim(\overleftarrow{C}_{2^n}(T)) \wedge Llim(\overleftarrow{C}_{2^{n-1}}(T)))$

Assume that \mathcal{M} is well-timed. Hence, *Eq. WT* holds. Then ψ holds at $\tau_{i+1,m}$ iff $tape(\alpha_i)[m] = tape(\alpha_{i+1})[m]$.

The head is at position m in σ_i iff at $\tau_{i+1,m}$ the following formula γ holds:

$$\gamma := \bigwedge_k (B_k \leftrightarrow ((\neg N)\mathbf{S}(N \wedge ((\neg N)\mathbf{S}(\bigvee_{q \in Q} S_q \wedge B_k))))$$

Indeed, this formula says that B_k holds at τ iff in the previous interval B_k holds at the (unique) position where $\bigvee_{q \in Q} S_q$ holds (this is the position of the head in the configuration σ_i). Hence, $T \rightarrow ((\neg\gamma) \rightarrow \psi)$ holds in every point of the interval $[i+1, i+2]$ iff $tape(\alpha_i)[m] = tape(\alpha_{i+1})[m]$ for every m different from the head position in σ_i .

Finally, φ_4 should express that $T \rightarrow ((\neg\gamma) \rightarrow \psi)$ holds at all points except the points of the interval $[0, 1]$. Note that $t \in [0, 1]$ iff $\overleftarrow{\diamond}(N \wedge \overleftarrow{\diamond}N)$ holds at t . Hence, φ_4 can be defined as follows: $\varphi_4 := (\overleftarrow{\diamond}(N \wedge \overleftarrow{\diamond}N) \rightarrow (T \rightarrow ((\neg\gamma) \rightarrow \psi)))$ \square

From Lemmas 4.3, 4.4, 4.5, 4.7, 4.8 we obtain:

Lemma 4.9 *For every $x \in \{0, 1\}^n$ let $Acc_{M,x}$ be $INIT_x \wedge \varphi_0 \wedge \varphi_1 \wedge \varphi_2 \wedge \varphi_3 \wedge \varphi_4 \wedge \overleftarrow{\diamond}q_{acc}$. Then $\mathcal{M}, 0 \models Acc_{M,x}$ iff \mathcal{M} represents a well-timed accepting computation sequence of M on x .*

The size $Acc_{M,x}$ is polynomial in the size of x , therefore this lemma together with Lemma 4.6 imply EXPSPACE hardness of the satisfiability problem for *TLC*.

5 Further Results

Often in the literature the temporal logics with modalities $\diamond_{(m,n)}(X)$ for integers $m < n$ are considered. These modalities are defined by the truth tables:

$$\diamond_{(m,n)}(X) : \quad \exists t((t_0 + m < t < t_0 + n) \wedge X(t))$$

The logic *QTLI* in addition to modalities \mathbf{U} and \mathbf{S} has infinity many modalities $\diamond_{(m,n)}(X)$ for all integers $m < n$. The logic *QTLI₀* is a fragment of *QTLI*; it has in addition to modalities \mathbf{U} and \mathbf{S} the modalities $\diamond_{(0,n)}(X)$, $\diamond_{(-n,0)}(X)$ for all natural n .

The logics *QTL*, *QTLI₀* and *QTLI* have the same expressive power (under arbitrary interpretations) and are equivalent to the logic *MITL* introduced in [1]. However, there is an exponential succinctness gap (under the binary coding) between *QTL* and *QTLI₀* and between *QTLI₀* and *QTLI*. The next theorem characterize the complexity of these logics [1].

Theorem 5.1 *1. The satisfiability problem for *QTLI₀* is PSPACE complete under the binary coding.*

2. The satisfiability problem for QTLI is EXPSPACE complete under the binary coding.

The theorem was proved for the finite variability interpretation in [1] and for arbitrary interpretation in [8, 15].

In this section we consider temporal logics with the modalities $C_k^{(n,m)}(X)$ and $Pn_k^{(m,n)}(X_1, \dots, X_k)$ for the integers $m < n$. These modalities are defined by the truth tables with free variable t_0 :

$$Pn_k^{(m,n)}(X_1, \dots, X_k) : \exists t_1 \dots \exists t_k (t_0 + m << t_1 < \dots < t_k < t_0 + n \wedge \bigwedge_{i=1}^k X_i(t_i))$$

$$C_k^{(m,n)}(X) : \exists t_1 \dots \exists t_k (t_0 + m < t_1 < \dots < t_k < t_0 + n \wedge \bigwedge_{i=1}^k X(t_i))$$

Note that Pn_k is equivalent to $Pn_k^{(0,1)}$ and C_k is equivalent to $C_k^{(0,1)}$

We consider the following temporal logics:

$$TLPI := TL(\mathbf{U}, \mathbf{S}, \{Pn_k^{(m,n)} : m < n\})$$

$$TLPI_0 := TL(\mathbf{U}, \mathbf{S}, \{Pn_k^{(0,n)}, Pn_k^{(-n,0)} : 0 < n\})$$

$$TLCI := TL(\mathbf{U}, \mathbf{S}, \{C_k^{(m,n)} : m < n\})$$

$$TLCI_0 := TL(\mathbf{U}, \mathbf{S}, \{C_k^{(0,n)}, C_k^{(-n,0)} : 0 < n\})$$

All these logics are expressively equivalent to TLC [11]. We investigate the complexity of the satisfiability problems for these logics under the unary and binary codings. Under the unary (respectively, binary) coding all the numbers which occur in the superscripts and subscripts of these modalities are coded in unary (respectively, in binary). The full version of this paper contains proofs of the results summarized in the following table:

Logic	unary coding	binary coding
$TLPI_0$	PSPACE complete	PSPACE complete
$TLPI$	PSPACE complete	EXPSPACE complete
$TLCI_0$	PSPACE complete	EXPSPACE complete
$TLCI$	PSPACE complete	EXPSPACE complete

Table 1. The complexity of the satisfiability problem

We conclude by a comparison of the expressive power of TLC and the expressive power of temporal logics with finitely many modalities.

Let $B = \{O_1^{l_1}, O_2^{l_2}, \dots\}$ be a finite set of modality names, and assume that every modality in B has a truth table definable in the monadic second-order logic of order with $\lambda x.x + 1$ function (we denote this logic by MLO^{+1}). MLO^{+1} is a very expressive (and undecidable) logic, and most of the modalities considered in the literature can be easily formalized in it. We proved in [12] that there is n (which depends on B) such that C_n is not expressible over the reals by a $TL(B)$

formulas. Hence, there is no temporal logic L which is at least as expressive as TLC over the reals, which has a finite set of modalities with truth tables in MLO^{+1} .

Our conjecture was that this result can be extended to the non-negative real line. However, the results of Sect. 3 refute this conjecture.

Indeed, let L be the temporal logic with the modalities \mathbf{U} , \mathbf{S} , \diamond_1 , $\overleftarrow{\diamond}_1$, \mathbf{nat} and \mathbf{even} , where \mathbf{nat} and \mathbf{even} are zero-arity modalities interpreted as the sets of natural and even numbers respectively. Corollary 3.3 shows that TLP , TLC and QTL are expressively equivalent over the class of proper structures, i.e., over the expansions of $\langle \mathbb{R}^+, <, \mathbb{N}, Even, Odd \rangle$ by unary predicates.

Hence, L is at least as expressive (over the class of non-negative real structures) as TLC . Over the non-negative reals, the modalities \mathbf{nat} and \mathbf{even} are easily definable by truth tables in MLO^{+1} (see Lemma 3.4). This refutes the conjecture.

Similarly to Corollary 3.3 one can show that TLP , TLC and QTL are expressively equivalent over the class of the expansions of $\langle \mathbb{R}, <, \mathbb{Z}, Even \rangle$ by unary predicates, where \mathbb{Z} and $Even$ are the sets of integers and even numbers. Hence, QTL with two additional zero-arity modalities for the set of integers and for the set of even numbers is at least as expressive as TLC . However, over the reals, these two modalities are not definable by truth tables in MLO^{+1} .

Acknowledgments

I am grateful to Yoram Hirshfeld for his insightful comments.

References

1. R. Alur, T. Feder, T.A. Henzinger. The Benefits of Relaxing Punctuality. *Journal of the ACM* 43 (1996) 116-146.
2. R. Alur, T.A. Henzinger. Logics and Models of Real Time: a survey. In *Real Time: Theory and Practice*. Editors de Bakker et al. LNCS 600 (1992) 74-106.
3. Baringer H. Barringer, R. Kuiper, A. Pnueli. A really abstract concurrent model and its temporal logic. *Proceedings of the 13th POPL* (1986), 173-183.
4. D.M. Gabbay, I. Hodkinson, M. Reynolds. *Temporal Logics volume 1*. Clarendon Press, Oxford (1994).
5. T.A. Henzinger It's about time: real-time logics reviewed. in *Concur 98*, *Lecture Notes in Computer Science* 1466, pp. 439-454. 1998.
6. T.H. Henzinger, J.F. Raskin, P.Y. Schobbens. The regular real time languages. *ICALP 1998*. pp 580-591.
7. Y. Hirshfeld and A. Rabinovich, A Framework for Decidable Metrical Logics. In *Proc. 26th ICALP Colloquium*, LNCS vol.1644, pp. 422-432, 1999.
8. Y. Hirshfeld and A. Rabinovich. Quantitative Temporal Logic. In *Computer Science Logic 1999*, LNCS vol. 1683, pp. 172-187, Springer Verlag 1999.
9. Y. Hirshfeld and A. Rabinovich, Logics for Real Time: Decidability and Complexity. *Fundam. Inform.* 62(1): 1-28 (2004).

10. Y. Hirshfeld and A. Rabinovich, Timer formulas and decidable metric temporal logic. *Information and Computation* Vol 198(2), pp. 148-178, 2005.
11. Y. Hirshfeld and A. Rabinovich. An Expressive Temporal Logic for Real Time. In *MFCS 2006*, Springer LNCS 4162, 492-504, 2006.
12. Y. Hirshfeld and A. Rabinovich, Expressiveness of Metric modalities for continuous time. *Logical methods in computer science* Volume 3, ISSUE 1, 2007
13. H. Kamp. *Tense Logic and the Theory of Linear Order*. Ph.D. thesis, University of California L.A. (1968).
14. Z. Manna, A. Pnueli. Models for reactivity. *Acta informatica* 30 (1993) 609-678.
15. C. Lutz, D. Walther and F. Wolter: Quantitative temporal logics over the reals: PSPACE and below, *Information and Computation*, 205(1):99-123 (2007).
16. M. Reynolds. The complexity of the temporal logic with until over general linear time, manuscript 1999.
17. T. Wilke. Specifying Time State Sequences in Powerful Decidable Logics and Time Automata. In *Formal Techniques in Real Time and Fault Tolerance Systems*. LNCS 863 (1994), 694-715.